

max.)

(50ns typ.)

TO ±1%

CAPABILITY

DRIVERS

# HIGH-SPEED CURRENT-MODE PWM

THE INFINITE POWER OF INNOVATION

## PRODUCTION DATA SHEET

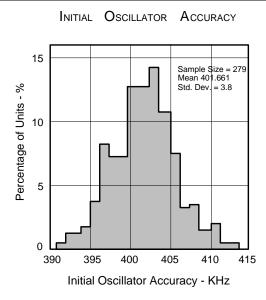
### DESCRIPTION

The SG1825C is a high-performance pulse width modulator optimized for high frequency current-mode power supplies. Included in the controller are a precision voltage reference, micro power start-up circuitry, soft start, highfrequency oscillator, wideband error amplifier, fast current limit comparator, full double-pulse suppression logic, and dual totem pole output drivers. Innovative circuit design and an advanced linear Schottky process result in very short propagation delays through the current limit comparator, logic, and output drivers. This device can be used to implement either current mode or voltagemode switching power supplies. It also is useful as a series-resonant controller to frequencies beyond 1MHz. The SG1825C is specified for operation over the full military ambient temperature range of -55°C to 125°C.

The SG2825C is characterized for the industrial range of  $-25^{\circ}$ C to  $85^{\circ}$ C, and the SG3825C is selected for the commercial range of 0°C to 70°C.

IMPORTANT: For the most current data, consult MICROSEMI's website: http://www.microsemi.com

### PRODUCT HIGHLIGHT



SOFTSTART DOUBLE-PULSE SUPPRESSION LOGIC WIDEBAND LOW-IMPEDANCE ERROR AMPLIFIER CURRENT-MODE OR VOLTAGE-MODE CONTROL

WIDE CHOICE OF HIGH-FREQUENCY PACKAGES

### **KEY FEATURES**

**KEY FEATURES** 

IMPROVED REFERENCE

INITIAL TOLERANCE (±1%

IMPROVED OSCILLATOR

**IMPROVED STARTUP** 

CURRENT (500µA typ.)

INITIAL ACCURACY (±3% typ.)

PROP DELAY TO OUTPUTS

5.1V REFERENCE TRIMMED

10V TO 30V OPERATION

1.5A PEAK TOTEM-POLE

NO OUTPUT DRIVER "FLOAT"

2MHZ OSCILLATOR

U.V. LOCKOUT WITH HYSTERESIS

PROGRAMMABLE

- AVAILABLE TO MIL-STD-883B
  MICROSEMI LEVEL "S"
- PROCESSING AVAIL.

	PACKAGE ORDER INFO									
Т <sub>Ј</sub> (°С)	Plastic DIP 16-Pin	DW Plastic SOIC 16-Pin	Q Plastic LCC 20-Pin	J Ceramic DIP 16-Pin	Ceramic LCC 20-Pin					
IJ( C)	RoHS Compliant / Pb-free Transition DC: 0503	RoHS Compliant / Pb-free Transition DC: 0516								
0 to 70	SG3825CN	SG3825CDW	SG32825CQ	SG3825CJ	-					
-25 to 85	SG2825CN	SG2825CDW	SG2825CQ	SG282CJ	-					
-55 to 125	-	-	-	SG1825CJ	SG1825CL					
MIL-STD-883	-	-	-	SG1825CJ/883B	SG1825CL/883					
DESC	-	-	-	SG1825CJ/DESC	SG1825CL/DESC					

Note: Available in Tape & Reel. Append the letters "TR" to the part number. (i.e. SG3825CN-TR)

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# Microsemi

Integrated Products Division 11861 Western Avenue, Garden Grove, CA. 92841, 714-898-8121, FAX: 714-893-2570

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# HIGH-SPEED CURRENT-MODE PWM

### Not Recommended for New Designs

ABSOLUTE MAXIMUM RATINGS	(Note 1)
RoHS Peak Package Solder Reflow Temp. (40 sec. max. exp.)	
Input Voltage $(V_{IN} \text{ and } V_{C})$	
Analog Inputs:	
Error Amplifier and Ramp	0.3V to 7.0V
Softstart and I <sub>LM</sub> /S.D	0.3V to 6.0V
Digital Input (Clock)	
Driver Outputs	
Source / Sink Output Current (each output):	C
Continuous	
Pulse, 500ns	
Softstart Sink Current	
Clock Output Current	
Error Amplifier Output Current	
Oscillator Charging Current	
Operating Junction Temperature:	····· /
Hermetic (J, L Package)	150°C
Plastic (DW, N, Q Packages)	
Storage Temperature Range	
Lead Temperature (soldering, 10 seconds)	
No. 1. Particular discussion of the second s	

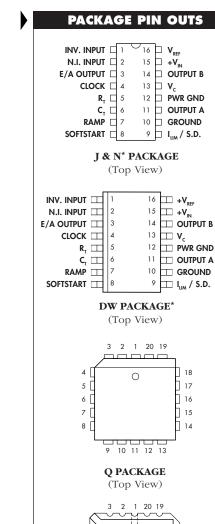
Note 1. Exceeding these ratings could cause damage to the device.

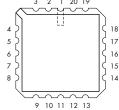
## THERMAL DATA

N PACKAGE:	
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\theta_{_{JA}}$	65°C/W
DW PACKAGE:	
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\boldsymbol{\theta}_{_{JA}}$	95°C/W
Q PACKAGE:	
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\boldsymbol{\theta}_{_{JA}}$	80°C/W
J PACKAGE:	
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\theta_{_{JA}}$	80°C/W
L PACKAGE:	
THERMAL RESISTANCE-JUNCTION TO CASE, $\theta_{\rm Jc}$	35°C/W
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\theta_{_{JA}}$	120°C/W

Junction Temperature Calculation:  $T_{I} = T_{A} + (P_{D} \times \theta_{IA}).$ 

The  $\theta_{jA}$  numbers are guidelines for the thermal performance of the device/pc-board system. All of the above assume no ambient airflow.





L PACKAGE (Top View)

1. N.C.	11. N.C.
2. INV. INPUT	12. I / S.D.
3. N.I. INPUT	13. GROUND
4. E/A OUTPUT	14. OUTPUT A
5. CLOCK	15. PWR GND
6. N.C.	16. N.C.
7. R,	17. V <sub>c</sub>
8. C,	18. OUTPUT B
9. RAMP	19. +V <sub>IN</sub>
10. SOFTSTART	20. V <sub>REF</sub>

\*DW & N Packages: RoHS / Pb-free 100% Matte Tin Lead Finish



# HIGH-SPEED CURRENT-MODE PWM

Not Recommended for New Designs

## RECOMMENDED OPERATING CONDITIONS (Note 2)

Davamator	Sumbol	Recommen	Units			
Parameter	Symbol	Min.	Тур.	Max.		
Supply Voltage Range		10		30	V	
Voltage Amp Common Mode Range		1.5		5.5	V	
Ramp Input Voltage Range		0		5.0	V	
Current Limit / Shutdown Voltage Range		0		4.0	V	
Source / Sink Output Current						
Continuous			200		mA	
Pulse, 500ns			1.0		А	
Voltage Reference Output Current		1		10	mA	
Oscillator Frequency Range		4		1500	kHz	
Oscillator Charging Current		0.030		3	mA	
Oscillator Timing Resistor	R <sub>T</sub>	1		100	kΩ	
Oscillator Timing Capacitor	CT	0.470		10	nF	
Operating Ambient Temperature Range:						
SG1825C	T <sub>A</sub>	0		70	°C	
SG2825C	T <sub>A</sub>	-25		85	°C	
SG3825C	T <sub>A</sub>	-55		125	°C	

Note 2. Range over which the device is functional.

## ELECTRICAL CHARACTERISTICS (Note 3)

(Unless otherwise specified, these specifications apply over the operating ambient temperatures for SG3825C with 0°C  $\leq T_A \leq 70°$ C, SG2825C with -25°C  $\leq T_A \leq 85°$ C, SG1825C with -55°C  $\leq T_A \leq 125°$ C, and  $V_{IN} = V_c = 15V$ . Low duty cycle pulse testing techniques are used which maintains junction and case temperatures equal to the ambient temperature.)

Parameter	Symbol	Symbol Test Conditions		SG1825C/2825C					
- Farameter	Symoor	Test conditions		Тур.	Max.	Min.	Тур.	Max.	Units
Reference Section									
Output Voltage		$T_{J} = 25^{\circ}C, I_{L} = 1mA$	5.05	5.10	5.15	5.05	5.10	5.15	V
Line Regulation		V <sub>IN</sub> = 10 to 30V		2	15		2	15	m٧
Load Regulation		I <sub>L</sub> = 1 to 10mA		5	15		5	15	m٧
Temperature Stability (Note 3)		Over Operating Temperature		0.2	0.4		0.2	0.4	mV/°C
Total Output Range (Note 3)		Over Line, Load, and Temperature	5.00		5.20	5.00		5.20	V
Output Noise Voltage (Note 3)		$f = 10Hz$ to $10kHz$ , $I_L = 0mA$		50	200		50		$\mu V_{RMS}$
Long Term Stability (Notes 3 &4)		T <sub>J</sub> = 125°C, t = 1000hrs		5	25		5	25	m٧
Short Circuit Current		V <sub>REF</sub> = OV	-15	-50	-100	-15	-50	-100	mA
Oscillator Section (Note 5)									
Initial Accuracy		$T_J = 25^{\circ}C$ , $C_{CLK} \leq 10 pF$	370	400	430	370	400	430	kHz
Voltage Stability		V <sub>IN</sub> = 10 to 30V		0.2	2		0.2	2	%
Temperature Stability (Note 3)		Over Rated Operating Temperature		5	8		5	8	%
Total Frequency Limits (Note 3)		Over Line and Temperature	350		450	350		450	kHz
Minimum Frequency		$R_{T} = 100 K\Omega, C_{T} = 0.01 \mu F$			4			4	kHz
Maximum Frequency		$R_{T} = 1K\Omega, C_{T} = 470 pF$	1.5			1.5			MHz
Clock High Level		$I_{cLK} = -1mA$	3.9	4.5		3.9	4.5		V
Clock Low Level		$I_{CLK} = -1mA$		2.3	2.9		2.3	2.9	V
Ramp Peak Voltage			2.6	2.8	3.0	2.6	2.8	3.0	V
Ramp Valley Voltage			0.7	1.0	1.25	0.7	1.0	1.25	V
Valley-to-Peak Amplitude			1.6	1.8	2.0	1.6	1.8	2.0	V

Note 3. This parameter is guaranteed by design and process control, but is not 100% tested in production.

Note 4. This parameter is non-accumulative, and represents the random fluctuation of the reference voltage within some error band when observed over any 1000 hour period of time.



# HIGH-SPEED CURRENT-MODE PWM

Not Recommended for New Designs

Parameter	Symbol	Test Conditions	<u>SG1</u>	825 <u>C/2</u>	825C	S	G382	5C	Ilmit
Falallieter	Symoor	Test conditions	Min.	Typ.	Max.	Min.	Тур.	Max.	Unit
Error Amplifier Section (Note 6	)								
Input Offset Voltage		$R_{s} \leq 2K\Omega$ , $V_{ERROR} = 2.5V$			15			15	m۷
Input Bias Current		$V_{error} = 2.5V$		0.6	3		0.6	3	μA
Input Offset Current		$V_{\text{ERROR}} = 2.5 V$		0.1	1		0.1	1	μA
DC Open Loop Gain	A <sub>VOL</sub>	$V_{ERROR} = 1 \text{ to } 4V$	60	95		60	95		dB
Common Mode Rejection		Over Rated Voltage Range, $V_{ERROR} = 2.5V$	75	95		75	95		dB
Power Supply Rejection		$V_{IN} = 10V$ to 30V, $V_{ERROR} = 2.5V$	85	110		85	110		dB
Output Sink Current		$V_{\text{ERROR}} = 1 V$	1	2.5		1	2.5		mA
Output Source Current		$V_{\text{ERROR}} = 4V$	-0.5	-1.3		-0.5	-1.3		m∕
Output High Voltage		I <sub>ERROR</sub> = -0.5mA	4.0	4.7	5.0	4.0	4.7	5.0	V
Output Low Voltage		$I_{\text{ERROR}} = 1 \text{mA}$	0	0.5	1.0	0	0.5	1.0	V
Unity Gain Bandwidth (Note 3)		A <sub>VOL</sub> = 0dB	3	5.5		3	5.5		MH
Slew Rate (Note 3)			6			6			V/µse
<b>PWM Comparator Section</b> (Not	e 5 & 7)		•						
Ramp Input Bias Current				-1	-5		-1	-5	μA
Minimum Duty Cycle		V <sub>ERROR</sub> = 1V			0			0	%
Maximum Duty Cycle (Note 8)		$V_{ERROR} = 4V$	85			85			%
Zero Duty Cycle Threshold			1.1	1.25		1.1	1.25		V
Delay to Driver Output (Note 3)		$V_{RAMP} = 0V \text{ to } 2V_{V} V_{ERROR} = 2V$		50	80		50	80	ns
Softstart Section	I								
C <sub>ss</sub> Charge Current		V <sub>SOFTSTART</sub> = 0.5V	3	9	20	3	9	20	μA
C <sub>ss</sub> Discharge Current		V <sub>SOFTSTART</sub> = 1.0V	1			1			m∕
Current Limit / Shutdown Section	on (Note 9)	•		1			1		
IIIIII Input Bias Current					±15			±10	μA
Current Limit Threshold			0.9	1.0	1.1	0.9	1.0	1.1	р <i>и</i> у
Shutdown Threshold			1.25	1.40	1.55	1.20	1.40	1.55	v
Delay to Driver Output (Note 3)		V <sub>SHUTDOWN</sub> = 0V to 1.2V	1.23	50	80	1.20	50	80	ns
Output Drivers Section (each o	utput)	SHUTDOWN - OV CO 1.2V		50	00		50	00	113
Output Low Level		1 - 90 m		0.25	0.40		0.25	0.40	v
Output Low Level		$I_{\text{SINK}} = 20\text{mA}$		1.2	2.0		1.2	2.0	v
Output High Level		$I_{\text{SINK}} = 200\text{mA}$	13.0	13.5	2.0	13.0	13.5	2.0	v
Output High Level		$I_{\text{SOURCE}} = 20\text{mA}$		13.0		12.0	13.0		v
V Standby Current		$I_{SOURCE} = 200 \text{mA}$ $V_c = 30 \text{V}$	12.0	13.0	500	12.0	150	500	
V <sub>c</sub> Standby Current				30	60		30	60	µA ns
Output Rise / Fall Time (Note 3)		$C_{L} = 1000 pF$		30	00		30	00	lis
Undervoltage Lockout Section							-		
Start Threshold Voltage			8.8	9.2	9.7	8.8	9.2	9.7	V
UV Lockout Hysteresis			0.4	0.8	1.2	0.4	0.8	1.2	V
Supply Current Section (Note 5	5)								
Start Up Current		$V_{IN} = 8V$		0.5	1.2		0.5	1.2	m∕
Operating Current		$V_{INV}$ $V_{RAMP}$ $V(I_{LIM}/S.D.) = 0V$ $V_{N.L} = 1V$		22	33		22	33	mA

Note 5.  $F_{OSC} = 400 \text{kHz}$  ( $R_T = 3.65 \text{k}\Omega$ ,  $C_T = 1.0 \text{nF}$ ). Note 6.  $V_{CM} = 1.5 \text{V}$  to 5.5 V. Note 7.  $V_{RAMP} = 0 \text{V}$ , unless otherwise specified. Note 8. 100% duty cycle is defined as a pulsewidth equal to one oscillator period.

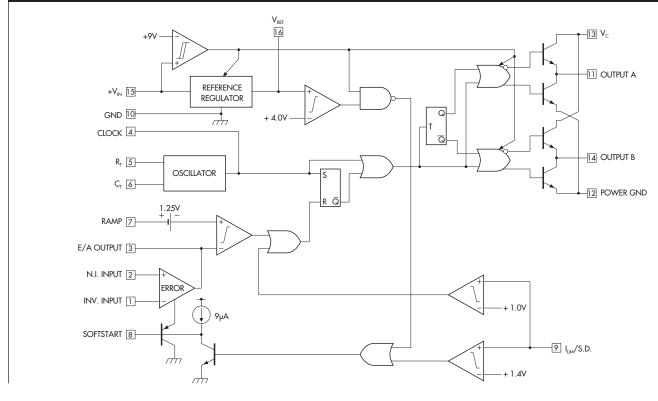
Note 9.  $V(I_{IIM}/S.D.) = 0V$  to 4.0V, unless otherwise specified.



# HIGH-SPEED CURRENT-MODE PWM

Not Recommended for New Designs

### **BLOCK DIAGRAM**



### FIGURE INDEX

### **Application Circuits**

#### FIGURE #

- 1. HIGH-SPEED LAYOUT AND BYPASSING
- 2. MICROPOWER STARTUP
- **3.** SOFTSTART FAST RESET
- 4. OSCILLATOR SYCHRONIZATION
- 5. OSCILLATOR FUNCTIONAL DIAGRAM
- **6.** VOLTAGE AMPLIFIER CONNECTIONS
- 7. DRIVING SHIELDED CABLE



## HIGH-SPEED CURRENT-MODE PWM

## Not Recommended for New Designs

### **APPLICATION INFORMATION**

### HIGH-SPEED LAYOUT AND BYPASSING

The SG1825C, like all high-speed circuits, requires extra attention to external conductor and component layout to minimize undesired inductive and capacitive effects. All lead lengths must be as short as possible. The best printed circuit board choice would be a four-layer design, with the two internal planes supplying power and ground. Signal interconnects should be placed on the outside, giving a conductor-over-ground-plane (microstrip) configuration. A two-sided printed circuit board with one side dedicated as a ground plane is next best, and requires careful component placement by a skilled pc designer.

Two supply bypass capacitors should be employed: a low-inductance 0.1µF ceramic within 0.25 inches of the  $+V_{IN}$  pin for high frequencies, and a 1 to 5µF solid tantalum within 0.5 inches of the  $V_C$  pin to provide an energy reservoir for the high-peak output currents. A low-inductance .01µF bypass for the reference output is also recommended.

#### **MICROPOWER STARTUP**

Since the SG1825C typically draws 700 $\mu$ A of supply current before turning on, a low power bleeder resistor from the rectified AC line supply is all that is required for startup. A start capacitor, C<sub>s</sub>, is charged with the excess current from the bleeder resistor. When the turn-on threshold voltage is reached, the PWM circuit becomes active, energizing the power transistors. The additional operating current required by the PWM is then provided by a bootstrap winding on the main high-frequency power transformer.

#### SOFTSTART CIRCUIT / OUTPUT DUTY CYCLE LIMIT

The softstart pin of the SG1825C is held low when either the chip is in the micropower mode, or when a voltage greater than +1.4 volts is present at the  $I_{LLM/S.D.}$  pin. The maximum positive swing of the voltage error amplifier is clamped to the Softstart pin voltage, providing a ramp-up of peak charging currents in the power semiconductors at turn-on.

In some cases, the duration of the Shutdown signal can be too short to fully discharge the softstart capacitor. The illustrated resistor/discrete PNP transistor configuration can be used to shorten the discharge time by a factor of 50 or more. When the internal discharge transistor in the SG1825C turns on, current will flow through surge limit resistor R1. As the resistor drop approaches 0.6 volts, the external PNP turns on, providing a low resistance discharge path for the energy in the softstart capacitor. The capacitor will be rapidly discharged to +0.7 volts, which corresponds to zero duty cycle in the pulse width modulator.

#### FREQUENCY SYNCHRONIZATION

Two or three SG1825C oscillators may be locked together with the interconnection scheme shown, if the devices are within an inch or so of each other. A master unit is programmed for desired frequency with  $R_T$  and  $C_T$  as usual. The oscillators in the slave units are disabled by grounding  $C_T$  and by connecting  $R_T$  to  $V_{REF}$ . The logic in the slave units is locked to the clock of the master with the wire-OR connection shown.

Many SG1825Cs can be locked to a master system clock by wiring the oscillators as slave units, and distributing the master clock to each using a tree-fanout geometry.

#### APPLICATION FIGURES

# FIGURE 1. — HIGH-SPEED LAYOUT and BYPASSING

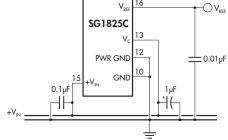
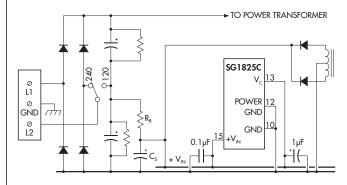


FIGURE 2. — MICROPOWER STARTUP





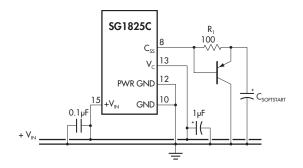
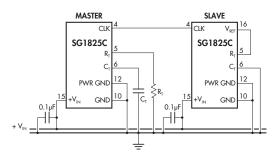


FIGURE 4. — OSCILLATOR SYCHRONIZATION





## HIGH-SPEED CURRENT-MODE PWM

## Not Recommended for New Designs

### APPLICATION INFORMATION

#### OSCILLATOR

The oscillator frequency is programmed by external timing components  $R_T$  and  $C_T$ . A nominal +3.0 volts appears at the  $R_T$  pin. The current flowing through  $R_T$  is mirrored internally with a 1:1 ratio. This causes an identical current to flow out the  $C_T$  pin, charging the timing capacitor and generating a linear ramp. When the upper threshold of +2.8 volts is reached, a discharge network reduces the ramp voltage to +1.0, where a new charge cycle begins.

The Clock output pin is LOW (+2.3 volts) during the charge cycle, and HIGH (+4.5 volts) during the discharge cycle. The Clock pin is driven by an NPN emitter follower, and so can be wire-ORed. Each Clock pin can drive a 1mA load. Since the internal current-source pulldown is approximately 400 $\mu$ A, the DC fan-out to other SG1825C Clock pins is at least two.

The type of capacitor selected for  $C_T$  is very important. At high frequencies, non-ideal characteristics such as effective series resistance (ESR), effective series inductance (ESL), dielectric loss and dielectric absorption all affect frequency accuracy and stability. RF capacitors such as silver mica, glass, polystrene, or COG ceramics are recommended. Avoid high-K ceramics, which work best in DC bypass applications.

#### ERROR AMPLIFIER

The voltage error amplifier is a true operational amplifier with lowimpedance output, and can be gain-stabilized using conventional feedback techniques. The typical DC open-loop gain is 95dB, with a single lowfrequency pole at 100Hz.

The input connections to the error amplifier are determined by the polarity of the power supply output voltage. For positive supplies, the common-mode voltage is +5.1 volts and the feedback connections in Figure A are used. With negative outputs, the common-mode voltage is half the reference, and the feedback divider is connected between the negative output and the +5.1 volt reference as shown in Figure B.

#### **OUTPUT DRIVER**

The output drivers are designed to provide up to 1.5 Amps peak output current. To minimize ringing on the output waveform, which can be destructive to both the power MOSFET and the PWM chip, the series inductance seen by the drivers should be as low as possible.

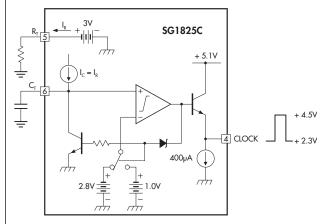
One solution is to keep the distance between the PWM and MOSFET gate as short as possible, and to use carbon composition series damping resistors. A Faraday shield to intercept radiated EMI from the power transistors is usually required with its choice.

A second approach is to place the MOSFETs some distance from the PWM chip, and use a series-terminated transmission line to preserve drive pulse fidelity. This will minimize noise radiated back to the sensitive analog circuitry of the SG1825C. A Faraday shield may also be required.

If the drivers are connected to an isolation transformer, or if kickback through  $C_{GD}$  of the MOSFET is severe, clamp diodes may be required. 1 Amp peak Schottky diodes will limit undershoot to less than -0.3 volts.

### APPLICATION FIGURES

### FIGURE 5. — OSCILLATOR FUNCTIONAL DIAGRAM





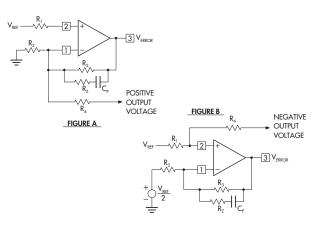


FIGURE 7. — DRIVING SHIELDED CABLE

